

Fenomenología de Gravitación Cuántica

Fiz1410-Primer Semestre 2008

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Prueba 1

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- Problema 1

(A) Considere la métrica de Robertson-Walker:

$$ds^2 = -dt^2 + a^2(t) \left(\frac{dr^2}{1-kr^2} + r^2(d\theta^2 + \sin^2\theta d\phi^2) \right)$$

Usando el lenguaje de formas diferenciales, encuentre:

(a) La conexión de spin.

(b) La forma de curvatura.

Sol:

$$\begin{aligned} e^0 &= dt; e^1 = a(t) \frac{dr}{\sqrt{1-kr^2}}; e^2 = a(t)r d\theta; e^3 = a(t)r \sin\theta d\phi \\ \omega_2^0 \wedge \frac{dr}{\sqrt{1-kr^2}} + \omega_3^0 \wedge r d\theta + \omega_4^0 \wedge r \sin\theta d\phi &= 0 \\ \dot{a} dt \wedge \frac{dr}{\sqrt{1-kr^2}} + \omega_0^1 \wedge dt + a(t)(\omega_2^1 \wedge r d\theta + \omega_3^1 \wedge r \sin\theta d\phi) &= 0 \\ \dot{a} dt \wedge r d\theta + a dr \wedge d\theta + \omega_0^2 \wedge dt + a(t)(\omega_1^2 \wedge \frac{dr}{\sqrt{1-kr^2}} + \omega_3^2 \wedge r \sin\theta d\phi) &= 0 \\ \dot{a} e^0 \wedge \frac{e^3}{a} + \frac{\sqrt{1-kr^2}}{a} e^1 \wedge \frac{e^3}{r} + \frac{e^2}{ar} \wedge \frac{e^3}{\operatorname{tg}\theta} + \omega_0^3 \wedge e^0 + \omega_1^3 \wedge e^1 + \omega_2^3 \wedge e^2 &= 0 \end{aligned}$$

Esto es:

$$\begin{aligned} \omega_1^0 \wedge e^1 + \omega_2^0 \wedge e^2 + \omega_3^0 \wedge e^3 &= 0 \\ \dot{a} e^0 \wedge \frac{e^1}{a} + \omega_0^1 \wedge e^0 + \omega_2^1 \wedge e^2 + \omega_3^1 \wedge e^3 &= 0 \\ \frac{\dot{a}}{a} e^0 \wedge e^2 + \sqrt{1-kr^2} e^1 \wedge \frac{e^2}{ar} + \omega_0^2 \wedge e^0 + \omega_1^2 \wedge e^1 + \omega_3^2 \wedge e^3 &= 0 \\ \dot{a} e^0 \wedge \frac{e^3}{a} + \frac{\sqrt{1-kr^2}}{a} e^1 \wedge \frac{e^3}{r} + \frac{e^2}{ar} \wedge \frac{e^3}{\operatorname{tg}\theta} + \omega_0^3 \wedge e^0 + \omega_1^3 \wedge e^1 + \omega_2^3 \wedge e^2 &= 0 \end{aligned}$$

Además:

$$\begin{aligned} \omega_i^0 &= -\omega_{0i} = \omega_{i0} = \omega_0^i \\ \omega_j^i &= -\omega_i^j \end{aligned}$$

Se obtiene:

$$\begin{aligned}\omega^0_1 &= \frac{\dot{a}}{a}e^1 = \omega^1_0 \\ \omega^2_0 &= \frac{\dot{a}}{a}e^2 = \omega^0_2 \\ \omega^2_1 &= \frac{\sqrt{1-kr^2}}{ar}e^2 = -\omega^1_2 \\ \omega^3_0 &= \frac{\dot{a}}{a}e^3 = \omega^0_3 \\ \omega^3_1 &= \frac{\sqrt{1-kr^2}}{ar}e^3 = -\omega^1_3 \\ \omega^3_2 &= \frac{1}{ar \operatorname{tg} \theta}e^3 = -\omega^2_3\end{aligned}$$

The curvature 2-forma es:

$$\begin{aligned}R^0_0 &= 0; R^0_1 = \frac{d^2 \ln(a)}{dt^2}e^0 \wedge e^1 - \frac{\dot{a}}{a}\omega^1_0 \wedge e^0 = \frac{d^2 \ln(a)}{dt^2}e^0 \wedge e^1 + \left(\frac{\dot{a}}{a}\right)^2 e^0 \wedge e^1; \\ R^0_2 &= \frac{d^2 \ln(a)}{dt^2}e^0 \wedge e^2 - \frac{\dot{a}}{a}(\omega^2_0 \wedge e^0 + \omega^2_1 \wedge e^1 + \omega^2_3 \wedge e^3) + \omega^0_1 \wedge \omega^1_2 + \omega^0_3 \wedge \omega^3_2 = \\ &= \frac{d^2 \ln(a)}{dt^2}e^0 \wedge e^2 - \frac{\dot{a}}{a}\left(\frac{\dot{a}}{a}e^2 \wedge e^0 + \frac{\sqrt{1-kr^2}}{ar}e^2 \wedge e^1\right) - \frac{\dot{a}}{a}e^1 \wedge \frac{\sqrt{1-kr^2}}{ar}e^2 = \frac{d^2 \ln(a)}{dt^2}e^0 \wedge e^2 + \left(\frac{\dot{a}}{a}\right)^2 e^0 \wedge e^2; \\ R^0_3 &= \frac{d^2 \ln(a)}{dt^2}e^0 \wedge e^3 - \frac{\dot{a}}{a}(\omega^3_0 \wedge e^0 + \omega^3_1 \wedge e^1 + \omega^3_2 \wedge e^2) + \omega^0_1 \wedge \omega^1_3 + \omega^0_2 \wedge \omega^2_3 = \\ &= \frac{d^2 \ln(a)}{dt^2}e^0 \wedge e^3 - \frac{\dot{a}}{a}\left(\frac{\dot{a}}{a}e^3 \wedge e^0 + \frac{\sqrt{1-kr^2}}{ar}e^3 \wedge e^1 + \frac{1}{ar \operatorname{tg} \theta}e^3 \wedge e^2\right) - \frac{\dot{a}}{a}e^1 \wedge \frac{\sqrt{1-kr^2}}{ar}e^3 - \frac{\dot{a}}{a}e^2 \wedge \\ &= \frac{1}{ar \operatorname{tg} \theta}e^3 = \frac{d^2 \ln(a)}{dt^2}e^0 \wedge e^3 + \left(\frac{\dot{a}}{a}\right)^2 e^0 \wedge e^3;\end{aligned}$$

$$R_{ab} = d\omega_{ab} + \omega_{ac} \wedge \omega_{db} \eta^{cd} = -d\omega_{ba} - \omega_{bd} \eta^{cd} \wedge \omega_{ca} = -R_{ba}$$

Por lo tanto:

$$\begin{aligned}R_{00} &= 0; R_{10} = \left(\frac{\dot{a}}{a}\right)^2 e^0 \wedge e^1; R_{20} = \left(\frac{\dot{a}}{a}\right)^2 e^0 \wedge e^2; R_{30} = \left(\frac{\dot{a}}{a}\right)^2 e^0 \wedge e^3; R_{11} = 0 \\ R_{21} &= R^2_1 = \frac{d}{dr} \frac{\sqrt{1-kr^2}}{r} \cdot \frac{\sqrt{1-kr^2}}{a^2} e^1 \wedge e^2 - \frac{\dot{a}}{a^2} \frac{\sqrt{1-kr^2}}{r} e^0 \wedge e^2 - \frac{\sqrt{1-kr^2}}{ar} (\omega^2_0 \wedge e^0 + \omega^2_1 \wedge \\ &= \frac{d}{dr} \frac{\sqrt{1-kr^2}}{r} \cdot \frac{\sqrt{1-kr^2}}{a^2} e^1 \wedge e^2 - \frac{\dot{a}}{a^2} \frac{\sqrt{1-kr^2}}{r} e^0 \wedge e^2 - \\ &= \frac{\sqrt{1-kr^2}}{ar} \left(\frac{\dot{a}}{a} e^2 \wedge e^0 + \frac{\sqrt{1-kr^2}}{ar} e^2 \wedge e^1\right) + \frac{\dot{a}}{a} e^2 \wedge \frac{\dot{a}}{a} e^1 = \left(\frac{d}{dr} \frac{\sqrt{1-kr^2}}{r} \cdot \frac{\sqrt{1-kr^2}}{a^2} + \left(\frac{\sqrt{1-kr^2}}{ar}\right)^2 - \left(\frac{\dot{a}}{a}\right)^2\right) e^1 \wedge e^2\end{aligned}$$

- Problema 2

Sea A una 1-forma con valores en el álgebra de Lie de un grupo G . Dada la transformación de gauge de A , con $g \in G$:

$$A' = g^{-1}A g + g^{-1}dg$$

(a) Mostrar que:

$$F = dA + A \wedge A \text{ transforma como}$$

$$F' = g^{-1}Fg$$

Suponga que, tanto A como g son matrices de $n \times n$.

Sea

$$S = \kappa \int \text{tr}(F \wedge \star F)$$

(b)Mostrar que S es invariante bajo la transformación de gauge de A .

(c) Encontrar las ecuaciones de movimiento para la 1-forma A .

La métrica de Minkowski es: $-+++$.

(d) Derive la identidad de Bianchi para F y pruebe que

$$\text{tr}(F^n) = \text{tr}(F \wedge F \dots \wedge F)$$

es cerrada.

Sol:

(c)

$$\begin{aligned} \delta S &= \kappa \delta(F, F) = 2\kappa(\delta F, F) = 2\kappa(d(\delta A) + \delta A \wedge A + A \wedge \delta A, F) = 2\kappa((\delta A, \delta F) + (\delta A \wedge A + A \wedge \delta A, F)) \\ &= 2\kappa \int \text{tr}(\delta A \wedge \star \delta F + \delta A \wedge A \wedge \star F + A \wedge \delta A \wedge \star F) = 2\kappa \int \text{tr}(\delta A \wedge \star \delta F + \delta A \wedge A \wedge \star F - \delta A \wedge \star F \wedge A) \end{aligned}$$

$$A_{ij} \wedge B_{jk} \wedge C_{ki} = -B_{jk} \wedge C_{ki} \wedge A_{ij}$$

Por lo tanto, la ecuación de movimiento es:

$$\star \delta F + A \wedge \star F - \star F \wedge A = 0, \text{ or}$$

$$\delta F + (-1)^{n-1} \star (A \wedge \star F - \star F \wedge A) = 0$$

(d)

$$d^2 A = 0 = dF - dA \wedge A + A \wedge dA = dF - (F - A \wedge A) \wedge A + A \wedge (F - A \wedge A) = dF - F \wedge A + A \wedge F$$

Encontremos

$$\begin{aligned} d \text{tr}(F^n) &= \text{tr}(dF \wedge F^{n-1}) + \text{tr}(F \wedge dF \wedge F^{n-2}) + \dots = 0, n \text{ par} \\ &= \text{tr}(F^{n-1} dF), n \text{ impar} \end{aligned}$$

Para el caso n impar:

$$\text{tr}(F^{n-1} dF) = \text{tr}(F^{n-1} \wedge F \wedge A) - \text{tr}(F^{n-1} \wedge A \wedge F) = \text{tr}(F^n \wedge A) - \text{tr}(F^n \wedge A) = 0$$

- Problema 3

Dado un sistema con n grados de libertad moviéndose bajo la restricción de r vínculos de Segunda Clase $\chi_a, a = 1, \dots, r$. Si H_c es el Hamiltoniano canónico del sistema:

(a) Encuentre el Hamiltoniano total.

(b) Defina el corchete de Dirac del sistema $(A, B)_D$. Muestre que:

- (i) $(A, B)_D = -(B, A)_D$
- (ii) $(A, BC)_D = (A, B)_D C + B(A, C)_D$
- (iii) $(A, B + C)_D = (A, B)_D + (A, C)_D$
- (iv) $(A, \alpha) = 0$, α constante.
- (v) $(A, (B, C)_D)_D + (B, (C, A)_D)_D + (C, (A, B)_D)_D = 0$ Identidad de Jacobi.

(c) Una partícula de masa m se mueve libremente en un círculo de radio R . Describa el movimiento de la partícula usando coordenadas cartesianas (x, y) en el plano:

- (i) Encuentre el Hamiltoniano canónico H_c
- (ii) Encuentre todos los vínculos y diga cuales son de Primera y Segunda Clase.
- (iii) Calcule el corchete de Dirac.
- (iv) Encuentre las ecuaciones canónicas en coordenadas cartesianas.

Sol:

(a)

$$0 = (H_c, \chi_b) + u_a (\chi_a, \chi_b); C_{ab} = (\chi_a, \chi_b)$$

$$u_a = - (H_c, \chi_b) C_{ba}^{-1}$$

$$H_T = H_c + u_a \chi_a = H_c - (H_c, \chi_b) C_{ba}^{-1} \chi_a$$

(b)

$$(H_T, G) = (H_c, G) - (H_c, \chi_b) C_{ba}^{-1} (\chi_a, G) = (H_c, G)_D$$

$$(i) (A, B)_D = (A, B) - (A, \chi_b) C_{ba}^{-1} (\chi_a, B) = - (B, A) + (B, \chi_b) C_{ba}^{-1} (\chi_a, A),$$

C antisimétrica

$$= - (B, A)_D$$

$$(ii) (A, BC)_D = (A, BC) - (A, \chi_b) C_{ba}^{-1} (\chi_a, BC) = (A, B)_D C + B(A, C)_D$$

(iii) Obvia (iv) Obvia

(c)

$$(i) H_c = \frac{p_x^2 + p_y^2}{2m}$$

$$(ii) \phi_1 = x^2 + y^2 - R^2 = 0; \phi_2 = x p_x + y p_y = 0,$$

los dos son de Segunda Clase, porque

$$(\phi_1, \phi_2) = 2x^2 + 2y^2 = 2R^2 \text{ no es cero}$$

$$(iii) (A, B)_D = (A, B) + (A, \phi_1) \frac{1}{2R^2} (\phi_2, B) - (A, \phi_2) \frac{1}{2R^2} (\phi_1, B)$$

$$\text{Verifiquemos: } (\phi_1, B)_D = 0; (\phi_2, B)_D = (\phi_2, B) - (\phi_2, B) = 0$$

$$(iv) \dot{x} = (x, H_c)_D =$$