

Fenomenología de Gravitación Cuántica

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Prueba 2

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- Problema 1

Sea S el espacio vectorial generado por las funciones cilíndricas:

$$\Psi_{\Gamma,f}[A] = f(U(A, \gamma_1), \dots, U(A, \gamma_L))$$

donde $U(A, \gamma)$ es la holonomía de A en γ .

(A) Se define

$$(\Psi_{\Gamma,f} | \Psi_{\Gamma,g}) = \int dU_1 \dots dU_L \overline{f(U_1, \dots, U_L)} g(U_1, \dots, U_L) \quad (1)$$

donde dU es la medida de Haar de $SU(2)$.

Demuestre que (1) define un producto interior en S .

Sol:

(i)

$$(\Psi_{\Gamma,f} | \Psi_{\Gamma,f}) = \int dU_1 \dots dU_L \overline{f(U_1, \dots, U_L)} f(U_1, \dots, U_L) \geq 0$$

$$\text{Si } \int dU_1 \dots dU_L \overline{f(U_1, \dots, U_L)} f(U_1, \dots, U_L) = 0 \\ \text{implica } f(U_1, \dots, U_L) = 0, \text{ esto es } \Psi_{\Gamma,f} = 0$$

(ii)

$$(\Psi_{\Gamma,f} | \Psi_{\Gamma,g}) = \overline{(\Psi_{\Gamma,g} | \Psi_{\Gamma,f})}, \text{ dado que } dU \text{ es real.}$$

(iii)

$$(\Psi_{\Gamma,g} | a\Psi_{\Gamma,f} + b\Psi_{\Gamma,h}) = a(\Psi_{\Gamma,g} | \Psi_{\Gamma,f}) + b(\Psi_{\Gamma,g} | \Psi_{\Gamma,h}), \forall a, b \in C$$

(B) Considere un estado de dos "loops" idénticos, $\alpha_1 = \alpha_2$, definido por

$$\Psi_{[\alpha]}[A] = \text{tr}(U(A, \alpha_1)U(A, \alpha_1)) \quad (2)$$

Encuentre la norma de este estado en el producto interior (1).

Sol:

$$(\Psi_{[\alpha]}[A]|\Psi_{[\alpha]}[A]) = \int dU |\text{tr}(U^2)|^2$$

Debemos encontrar:

$$A_{ijkl, mn pq} = \int dU \overline{U_{ij} U_{kl}} U_{mn} U_{pq}$$

Cambiemos variables: $U \rightarrow V_1 UV_2$

Por lo tanto:

$$A_{ijkl, mn pq} = V_2^\dagger{}_{ja} V_1^\dagger{}_{bi} V_2^\dagger{}_{lc} V_1^\dagger{}_{dk} V_1{}_{me} V_2{}_{fn} V_1{}_{ph} V_2{}_{rq} A_{badc, e f h r} \quad (3)$$

Esto es:

$$A_{badc, e f h r} = \lambda_{1 bd, eh} \delta_{af} \delta_{cr} + \lambda_{2 bd, eh} \delta_{ar} \delta_{cf} \quad (4)$$

Insertando (4) en (3), se tiene:

$$\lambda_{\alpha ik, mp} = V_1^\dagger{}_{bi} V_1^\dagger{}_{dk} V_1{}_{me} V_1{}_{ph} \lambda_{\alpha bd, eh} \quad \alpha = 1, 2 \quad (5)$$

Se tiene:

$$\lambda_{\alpha bd, eh} = \mu_{\alpha 1} \delta_{eb} \delta_{hd} + \mu_{\alpha 2} \delta_{ed} \delta_{hb}$$

Resumiendo,

$$A_{badc, e f h r} = \mu_{11} \delta_{eb} \delta_{hd} \delta_{af} \delta_{cr} + \mu_{12} \delta_{ed} \delta_{hb} \delta_{af} \delta_{cr} + \mu_{21} \delta_{eb} \delta_{hd} \delta_{ar} \delta_{cf} + \mu_{22} \delta_{ed} \delta_{hb} \delta_{ar} \delta_{cf} \quad (6)$$

Contrayendo $b = e, d = h$, obtenemos:

$$4\mu_{11} \delta_{af} \delta_{cr} + 2\mu_{12} \delta_{af} \delta_{cr} + 4\mu_{21} \delta_{ar} \delta_{cf} + 2\mu_{22} \delta_{ar} \delta_{cf} = \delta_{af} \delta_{cr}$$

Esto es:

$$4\mu_{11} + 2\mu_{12} = 1, 2\mu_{21} + \mu_{22} = 0$$

Contrayendo $b = h, d = e$, obtenemos:

$$2\mu_{11} \delta_{af} \delta_{cr} + 4\mu_{12} \delta_{af} \delta_{cr} + 2\mu_{21} \delta_{ar} \delta_{cf} + 4\mu_{22} \delta_{ar} \delta_{cf} = \delta_{ar} \delta_{cf}$$

Esto es,

$$\mu_{11} + 2\mu_{12} = 0, 4\mu_{22} + 2\mu_{21} = 1$$

$$\mu_{12} = -\frac{1}{6}, \mu_{11} = \frac{1}{3}, \mu_{21} = -\frac{1}{6}, \mu_{22} = \frac{1}{3}$$

Por lo tanto:

$$A_{badc,efhr} = \frac{1}{3}(\delta_{eb}\delta_{hd}\delta_{af}\delta_{cr} + \delta_{ed}\delta_{hb}\delta_{ar}\delta_{cf}) - \frac{1}{6}(\delta_{ed}\delta_{hb}\delta_{af}\delta_{cr} + \delta_{eb}\delta_{hd}\delta_{ar}\delta_{cf}) \quad (7)$$

Verifiquemos $b = e, a = f$ da:

$$\frac{1}{3}(4\delta_{hd}\delta_{cr} + \delta_{hd}\delta_{cr}) - \frac{1}{6}(2\delta_{hd}\delta_{cr} + 2\delta_{hd}\delta_{cr}) = \delta_{hd}\delta_{cr}$$

Correcto.

Otro test:

$$\epsilon_{mp}\epsilon_{nq} \int dU \overline{U_{ij}U_{kl}} U_{mn} U_{pq} = 2 \int dU \overline{U_{ij}U_{kl}} = \epsilon_{ik}\epsilon_{jl}$$

Se tiene, de (7):

$$\epsilon_{eh}\epsilon_{fr}[\frac{1}{3}(\delta_{eb}\delta_{hd}\delta_{af}\delta_{cr} + \delta_{ed}\delta_{hb}\delta_{ar}\delta_{cf}) - \frac{1}{6}(\delta_{ed}\delta_{hb}\delta_{af}\delta_{cr} + \delta_{eb}\delta_{hd}\delta_{ar}\delta_{cf})] = \epsilon_{bd}\epsilon_{ac}[\frac{2}{3} - \frac{1}{6}(-1 - 1)] = \epsilon_{bd}\epsilon_{ac}$$

Correcto.

Finalmente,

$$(\Psi_{[\alpha]}[A]|\Psi_{[\alpha]}[A]) = \int dU \overline{U_{ij}U_{ji}U_{kl}U_{lk}} = \frac{1}{3}(4+4) - \frac{1}{6}(2+2) = 2$$

Por lo tanto $N = \sqrt{2}$

- Problema 2

La acción de Einstein-Hilbert-Cartan está dada por:

$$S[e, \omega] = \frac{1}{16\pi G} \int \epsilon_{IJKL} (\frac{1}{4}e^I \wedge e^J \wedge e^K \wedge e^L - R(\omega)^{KL} - \frac{1}{12}\lambda e^I \wedge e^J \wedge e^K \wedge e^L)$$

G es la constante de Newton y λ es la constante cosmológica. $R(\omega)^{KL}$ es la forma de curvatura correspondiente a la conexión de espín ω .

(A) Encuentre la ecuación de movimiento que se obtiene al variar ω . Escriba esta ecuación usando la forma de torsión.

Sol:

$$\begin{aligned}
\delta R(\omega)^{KL} &= d\delta\omega^{KL} + \delta\omega^K{}_J \wedge \omega^{JL} + \omega^K{}_J \wedge \delta\omega^{JL}, \\
\delta S[e, \omega] &= \int \epsilon_{IJKL} (-d(e^I \wedge e^J) \wedge \delta\omega^{KL} - \omega_M{}^L \wedge \delta\omega^{KM} + \omega^K{}_M \wedge \delta\omega^{ML}) = 0, \\
\epsilon_{IJKM} (-d(e^I \wedge e^J)) + (\epsilon_{IJKL} e^I \wedge e^J \wedge \omega_M{}^L - \epsilon_{IJML} e^I \wedge e^J \wedge \omega_K{}^L) &= 0, \quad \omega^{LM} = -\omega^{ML} \\
S[e, \omega] &= \frac{1}{16\pi G} \int \epsilon_{IJKL} \left(\frac{1}{4} e^I \wedge e^J \wedge R(\omega)^{KL} - \frac{1}{12} \lambda e^I \wedge e^J \wedge e^K \wedge e^L \right) \\
\delta S &= \frac{1}{16\pi G} \int \epsilon_{IJKL} \left(\frac{1}{2} \delta e^I \wedge e^J \wedge R(\omega)^{KL} + \frac{1}{4} e^I \wedge e^J \wedge \delta R(\omega)^{KL} - \frac{1}{3} \lambda \delta e^I \wedge e^J \wedge e^K \wedge e^L \right)
\end{aligned}$$

Therefore:

$$\begin{aligned}
\epsilon_{IJKL} (e^J \wedge R(\omega)^{KL} - \frac{2}{3} \lambda e^J \wedge e^K \wedge e^L) &= 0 \\
\delta R(\omega)^{KL} &= d\delta\omega^{KL} + \delta\omega^K{}_J \wedge \omega^{JL} + \omega^K{}_J \wedge \delta\omega^{JL} \\
\int \epsilon_{IJKL} e^I \wedge e^J \wedge (d\delta\omega^{KL} + \delta\omega^K{}_M \wedge \omega^{ML} + \omega^K{}_M \wedge \delta\omega^{ML}) &= \int \epsilon_{IJKL} (-d(e^I \wedge e^J) \wedge \delta\omega^{KL} - e^I \wedge e^J \wedge \omega_M{}^L \wedge \delta\omega^{KM} + e^I \wedge e^J \wedge \omega_K{}^M \wedge \delta\omega^{ML}) = 0, \\
\epsilon_{IJKM} (-d(e^I \wedge e^J)) - \frac{1}{2} (\epsilon_{IJKL} e^I \wedge e^J \wedge \omega_M{}^L - \epsilon_{IJML} e^I \wedge e^J \wedge \omega_K{}^L) - \frac{1}{2} (\epsilon_{IJKL} e^I \wedge e^J \wedge \omega^L{}_M - \epsilon_{IJKL} e^I \wedge e^J \wedge \omega^L{}_K) &= 0
\end{aligned}$$

P.D. Last equation implies $T^I = 0$

The action is invariant under local Lorentz rotations in capital latin indices, so last equation must be covariant under local Lorentz. The only Lorents 1- form vectors are e^I, T^J . Therefore, last equation must be linear combinations of $e^I \wedge T^J$. Let us show this point explicitly.

$$\begin{aligned}
\epsilon_{IJKM} (-d(e^I \wedge e^J)) - \frac{1}{2} (\epsilon_{IJKL} e^I \wedge e^J \wedge \omega_M{}^L - \epsilon_{IJML} e^I \wedge e^J \wedge \omega_K{}^L) - \frac{1}{2} (\epsilon_{IJKL} e^I \wedge e^J \wedge \omega^L{}_M - \epsilon_{IJKL} e^I \wedge e^J \wedge \omega^L{}_K) &= 0 \\
\epsilon_{IJKM} (-T^I \wedge e^J + e^I \wedge T^J) + \epsilon_{IJKM} (\omega_A^I \wedge e^A \wedge e^J + \omega_A^J \wedge e^I \wedge e^A) &= 0 \\
-\frac{1}{2} (\epsilon_{IJKL} e^I \wedge e^J \wedge \omega_M{}^L - \epsilon_{IJML} e^I \wedge e^J \wedge \omega_K{}^L) - \frac{1}{2} (\epsilon_{IJKL} e^I \wedge e^J \wedge \omega^L{}_M - \epsilon_{IJKL} e^I \wedge e^J \wedge \omega^L{}_K) &= 0
\end{aligned}$$

$$\begin{aligned}
K = 0, M = 1 \\
\omega_A^2 \wedge e^A \wedge e^3 + \omega_A^3 \wedge e^2 \wedge e^A - \omega_A^3 \wedge e^A \wedge e^2 - \omega_A^2 \wedge e^3 \wedge e^A \\
-\frac{1}{2} (\epsilon_{IJ0L} e^I \wedge e^J \wedge \omega_1{}^L - \epsilon_{IJ1L} e^I \wedge e^J \wedge \omega_0{}^L) - \frac{1}{2} (\epsilon_{IJL0} e^I \wedge e^J \wedge \omega_1{}^L - \epsilon_{IJ1L} e^I \wedge e^J \wedge \omega_0{}^L) &= \\
2\omega_A^2 \wedge e^A \wedge e^3 + 2\omega_A^3 \wedge e^2 \wedge e^A - (\epsilon_{LIJ} e^I \wedge e^J \wedge \omega_1{}^L - \epsilon_{IJ1L} e^I \wedge e^J \wedge \omega_0{}^L) &= \\
2\omega_0^2 \wedge e^0 \wedge e^3 + 2\omega_0^3 \wedge e^2 \wedge e^0 + 2\omega_1^2 \wedge e^1 \wedge e^3 + 2\omega_1^3 \wedge e^2 \wedge e^1 - (2e^1 \wedge e^2 \wedge \omega_1{}^3 + 2e^3 \wedge e^1 \wedge \omega_1{}^2) - 2e^3 \wedge e^0 \wedge \omega_0{}^2 - 2e^0 \wedge e^2 \wedge \omega_0{}^3 &= 0
\end{aligned}$$

That is:

$$\epsilon_{IJKM} (-e^J \wedge T^I + e^I \wedge T^J) = 0$$

Taking dual, we get:

$$-e^J \wedge T^I + e^I \wedge T^J = 0$$

Write:

$$\begin{aligned}
 T^I &= T^I_{AB} e^A \wedge e^B \\
 -T^I_{AB} e^A \wedge e^B \wedge e^J + T^J_{AB} e^A \wedge e^B \wedge e^I &= 0 \\
 -T^I_{AB} \epsilon^{ABJL} + T^J_{AB} \epsilon^{ABIL} &= 0 \\
 \tilde{T}^{IJL} &= \tilde{T}^{JIL}
 \end{aligned}$$

That is \tilde{T}^{IJL} is symmetric in the two first indices
and antisymmetric in the last two.

$$\tilde{T}^{IJL} = \tilde{T}^{JIL} = -\tilde{T}^{JLI} = -\tilde{T}^{LJI} = \tilde{T}^{LIJ} = \tilde{T}^{ILJ} = -\tilde{T}^{IJL}$$

Therefore, $\tilde{T}^{IJL} = 0, T^I_{AB} = 0$

(B) Encuentre la ecuación de movimiento que se obtiene al variar e^I . Muestre que esta ecuación es equivalente a la ecuación de Einstein en el vacío en lenguaje tensorial.

Sol:

$$\begin{aligned}
 \delta S &= \frac{1}{16\pi G} \int \epsilon_{IJKL} \left(\frac{1}{2} \delta e^I \wedge e^J \wedge R(\omega)^{KL} + \frac{1}{4} e^I \wedge e^J \wedge \delta R(\omega)^{KL} - \frac{1}{3} \lambda \delta e^I \wedge e^J \wedge e^K \wedge e^L \right) \\
 &\quad \epsilon_{IJKL} (e^J \wedge R(\omega)^{KL} - \frac{2}{3} \lambda e^J \wedge e^K \wedge e^L) = 0 \\
 &\quad \epsilon_{IJKL} (e^J_{\mu} R^{KL}_{\nu\lambda} - \frac{2}{3} \lambda e^J_{\mu} e^K_{\nu} e^L_{\lambda}) dx^{\mu} \wedge dx^{\nu} \wedge dx^{\lambda} = \\
 &\quad (\epsilon_{IJKL} e^J_{\mu} e^K_{\alpha} e^L_{\beta} R^{\alpha\beta}_{\nu\lambda} - \frac{2}{3} \epsilon_{IJKL} \lambda e^J_{\mu} e^K_{\nu} e^L_{\lambda}) dx^{\mu} \wedge dx^{\nu} \wedge dx^{\lambda} = 0 \\
 &\quad \text{multiply by } e^I_{\rho} \\
 &\quad (\epsilon_{\rho\mu\alpha\beta} e R^{\alpha\beta}_{\nu\lambda} - \frac{2}{3} \lambda e \epsilon_{\rho\mu\nu\lambda}) dx^{\mu} \wedge dx^{\nu} \wedge dx^{\lambda} = 0
 \end{aligned}$$

Taking dual:

$$\begin{aligned}
 &(\epsilon_{\rho\mu\alpha\beta} e R^{\alpha\beta}_{\nu\lambda} - \frac{2}{3} \lambda e \epsilon_{\rho\mu\nu\lambda}) \epsilon^{\mu\nu\lambda\eta} = 0 \\
 &\epsilon_{\rho\mu\nu\lambda} \epsilon^{\mu\nu\lambda\eta} = -6\delta^{\eta}_{\rho} \\
 &4R^{\eta}_{\rho} - 2R\delta^{\eta}_{\rho} + 4\lambda\delta^{\eta}_{\rho} = 0
 \end{aligned}$$

- Problema 3

Muestre que la conexión de espín ω se puede escribir de la siguiente forma:

$$\omega_{\mu}^{IJ} = A_{\mu}^{IJ} + B_{\mu}^{IJ}$$

donde A es auto-dual y B es anti-auto-dual.

$$iK_{\mu}^{IJ} = \pm \frac{1}{2} \epsilon_{MN}^{IJ} K_{\mu}^{MN}, \text{ para auto-dual (+), anti-auto-dual (-)}$$

Encuentre A y B como función de ω .

Sol:

$$\begin{aligned}
 \frac{1}{2} \epsilon_{MN}^{IJ} \omega_{\mu}^{MN} &= iA_{\mu}^{IJ} - iB_{\mu}^{IJ} \\
 i\omega_{\mu}^{IJ} &= iA_{\mu}^{IJ} + iB_{\mu}^{IJ} \\
 A_{\mu}^{IJ} &= \frac{1}{2i} \left(\frac{1}{2} \epsilon_{MN}^{IJ} \omega_{\mu}^{MN} + i\omega_{\mu}^{IJ} \right) = \frac{1}{2} \left(-i\frac{1}{2} \epsilon_{MN}^{IJ} \omega_{\mu}^{MN} + \omega_{\mu}^{IJ} \right) \\
 B_{\mu}^{IJ} &= \frac{1}{2i} \left(-\frac{1}{2} \epsilon_{MN}^{IJ} \omega_{\mu}^{MN} + i\omega_{\mu}^{IJ} \right) = \frac{1}{2} \left(i\frac{1}{2} \epsilon_{MN}^{IJ} \omega_{\mu}^{MN} + \omega_{\mu}^{IJ} \right)
 \end{aligned}$$