# Variational principle for the asymptotic speed of fronts of the density-dependent diffusion-reaction equation 

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#### Abstract

We show that the minimal speed for the existence of monotonic fronts of the equation $u_{t}=\left(u^{m}\right)_{x x}+f(u)$ with $f(0)=f(1)=0, m>1$ and $f>0$ in ( 0,1 ), is derived from a variational principle. The variational principle allows us to calculate, in principle, the exact speed for general $f$. The case $m=1$ when $f^{\prime}(0)=0$ is included as an extension of the results.


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Several problems arising in population growth [1,2] combustion theory [3,4], chemical kinetics [5], and others [6], lead to an equation of the form

$$
\frac{\partial \rho}{\partial t}+\vec{\nabla} \cdot \vec{j}=F(\rho)
$$

where the source term $F(\rho)$ represents net growth and saturation processes. The flux $\vec{j}$ is given by Fick's law

$$
\vec{j}=-D(\rho) \vec{\nabla} \rho
$$

where the diffusion coefficient $D(\rho)$ may depend on the density or in simple cases be taken as a constant. In one dimension this leads to the equation

$$
\begin{equation*}
\frac{\partial \rho}{\partial t}=\frac{\partial}{\partial x}\left[D(\rho) \frac{\partial \rho}{\partial x}\right]+F(\rho) \tag{1a}
\end{equation*}
$$

In what follows we shall assume that

$$
\begin{equation*}
F(\rho)>0 \text { in }(0,1), \quad F(0)=F(1)=0, \tag{1b}
\end{equation*}
$$

restrictions which are satisfied by several models. When the diffusion coefficient is constant and the additional requirement $F^{\prime}(0)>0$ is satisfied, the asymptotic speed of propagation of localized small perturbations to the unstable state $u=0$ is bounded below and in some cases coincides [7] with the value $c_{L}=2 \sqrt{F^{\prime}(0)}$, which is obtained from considerations on the linearized equation [8]. However, when either $F^{\prime}(0)=0$ or $D(\rho)$ is not a constant, no hint for the speed of propagation of disturbances can be obtained from linear theory alone. A common choice for the diffusion coefficient is a power law, a case with which we shall be concerned here. Therefore the equation that we study is

$$
\begin{equation*}
\frac{\partial \rho}{\partial t}=\left(\rho^{m}\right)_{x x}+F(\rho) \tag{2a}
\end{equation*}
$$

with

$$
\begin{equation*}
F(0)=F(1)=0, \quad F>0 \text { in }(0,1) . \tag{2b}
\end{equation*}
$$

Aronson [2] and Aronson and Weinberger [7] have shown that the asymptotic speed of propagation of disturbances from rest is the minimal speed $c^{*}(m)$ for which there exist monotonic traveling fronts $\rho(x, t)=q(x-c t)$
joining $q=1$ to $q=0$. The equation satisfied by the traveling fronts is

$$
\begin{equation*}
\left(q^{m}\right)_{z z}+c q_{z}+F(q)=0, \tag{3a}
\end{equation*}
$$

with

$$
\begin{equation*}
q(-\infty)=1, \quad q>0, \quad q^{\prime}<0 \text { in }(-\infty, \omega), \quad q(\omega)=0, \tag{3b}
\end{equation*}
$$

where $z=x-c t$. The wave of minimal speed is sharp; that is, $\omega<\infty$ when $m>1$ [2].

An explicit solution is known [1,2] for the case $F(q)=q(1-q)$ and $m=2$; the wave form is given by

$$
q(z)=\left(1-\frac{1}{2} e^{z / 2}\right)_{+},
$$

and it travels with speed $c^{*}(2)=1$ (here $[x]_{+}$ $\equiv \max (x, 0)\}$. Recently the derivative $d c / d m$ at $m=2$ has been calculated by two different methods. Its value is $-\frac{7}{24}[9,10]$. Other exact solutions for different choices for $m$ and $F$ have been given in [11].

The purpose of this work is to give a variational characterization of the minimal speed $c^{*}(m)$ for Eq. (3) when $m>1$, and as a by-product for the case $m=1$ when $F^{\prime}(0)=0$, both cases for which no information is obtained from linear theory. The case $m=1$ with $F^{\prime}(0)>0$ has been studied elsewhere [13]. Lower bounds have been obtained on the minimal speed $c^{*}(m)$ [12]; the present results allow its exact calculation for arbitrary $f$.

Since the selected speed corresponds to that of a decreasing monotonic front, we may consider the dependence of its derivative $d q / d z$ on $q$. Calling $p(q)=-q^{m-1} d q / d z$, where the minus sign is included so that $p$ is positive, we find that the monotonic fronts are solutions of

$$
\begin{equation*}
p \frac{d p}{d q}-\frac{c^{*}}{m} p+\frac{1}{m} q^{m-1} F(q)=0 \tag{4a}
\end{equation*}
$$

with

$$
\begin{equation*}
p(0)=p(1)=0, \quad p>0 \text { in }(0,1) . \tag{4b}
\end{equation*}
$$

Although the wave of minimal speed is sharp and therefore $q^{\prime}(0)<0$, by the definition of $p, p(0)=0$. We now show that the minimal speed $c^{*}(m)$ follows from a varia-
tional principle whose Euler equation is Eq. (4a).
Let $g$ be a positive function such that $h=-g^{\prime}>0$. Multiplying Eq. (4a) by $g / p$ and integrating we obtain after integration by parts,

$$
\begin{equation*}
\frac{c^{*}}{m}=\frac{\int_{0}^{1}\left[\frac{1}{m} q^{m-1} F(q) \frac{g(q)}{p(q)}+h(q) p(q)\right]}{\int_{0}^{1} g(q) d q} . \tag{5}
\end{equation*}
$$

By Schwarz's inequality, since $q, F, g$, and $h$ are positive, we know

$$
\begin{equation*}
\frac{1}{m} q^{m-1} F \frac{g}{p}+h p \geq 2\left(\frac{1}{m} q^{m-1} F g h\right)^{1 / 2} \tag{6}
\end{equation*}
$$

and therefore, replacing in Eq. (5) we have

$$
\begin{equation*}
c^{*} \geq 2 \frac{\int_{0}^{1} \sqrt{m q^{m-1} F g h} d q}{\int_{0}^{1} g d q} \tag{7}
\end{equation*}
$$

This bound has been already given by us [12]. We now show that it is always possible to find a $g(q)$ such that the equality in Eq. (6) and therefore also in Eq. (7) holds. We do so by explicit construction of such a function $g$. The equality in Eq. (6) holds if

$$
\begin{equation*}
\frac{1}{m} q^{m-1} F \frac{g}{p}=h p \tag{8}
\end{equation*}
$$

Let $v(q)$ be the positive solution of

$$
\begin{equation*}
\frac{v^{\prime}}{v}=\frac{c^{*}}{m p} \tag{9a}
\end{equation*}
$$

and choose

$$
\begin{equation*}
g=\frac{1}{v^{\prime}} \tag{9b}
\end{equation*}
$$

We have then

$$
\frac{v^{\prime \prime}}{v}=\frac{\left(v^{\prime}\right)^{2}}{v^{2}}-\frac{c^{*}}{m p^{2}} p^{\prime}=\frac{c^{*}}{m^{2} p^{3}} q^{m-1} F(q)
$$

where we have used Eq. (9a) to eliminate $v^{\prime}$ and Eq. (4a) to eliminate $p^{\prime}$. Therefore,

$$
\begin{equation*}
h=-g^{\prime}=\frac{v^{\prime \prime}}{\left(v^{\prime}\right)^{2}}=\frac{1}{m p^{2}} q^{m-1} F g>0 \tag{9c}
\end{equation*}
$$

where we have made use of Eqs. (9a) and (9b). With this expression for $h$, we can see that Eq. (8) is satisfied. In addition we must check that $g$ as we have defined it is such that its integral exists. In fact it exists and, moreover, one can always normalize $g$ so that $g(0)=1$ and $g(1)=0$. From the definition of $g$ we obtain

$$
\begin{equation*}
g(q)=\frac{m p(q)}{c^{*}} \exp \left[-\int_{q 0}^{q} \frac{c^{*}}{m p} d q^{\prime}\right] \tag{9d}
\end{equation*}
$$

where $0<q_{0}<1$. Since $p(1)=0$ and $p$ is positive between 0 and 1 it follows that $g(1)=0$. At zero no divergence occurs, as we now show. Call $\hat{c}=c^{*} / m$ and $f(q)=q^{m-1} F(q) / m$. Then Eq. (4a) reads

$$
\begin{equation*}
p p^{\prime}-\widehat{c} p+f=0 \tag{10a}
\end{equation*}
$$

with

$$
\begin{equation*}
f(0)=f(1)=0 \quad \text { and } f^{\prime}(0)=0 \tag{10b}
\end{equation*}
$$

For this case Aronson and Weinberger [7] have shown that $p(q)$ approaches the fixed point $q=0$ as $p=\widehat{c} q=c^{*} q / m$. Then, from (9a) it follows that $v^{\prime} / v \approx 1 / q$ near zero, i.e., $v \approx A q$ near zero. Choosing $A=1$ and using (9b) we have that $g(0)=1$. That $g(0)=1$ can also be derived from the explicit formula for $g(q)$ given in ( 9 d ) (through a careful analysis of the divergence of the integral near zero). Then the integral of $g$ exists. We have shown then

$$
\begin{equation*}
c^{*}(m)=\max \left[2 \frac{\int_{0}^{1} \sqrt{m q^{m-1} F g h} d q}{\int_{0}^{1} g d q}\right] \tag{11}
\end{equation*}
$$

where the maximum is taken over all functions $g$ such that

$$
g(0)=1, \quad g(1)=0 \text { and } h=-g^{\prime}>0
$$

It is perhaps of some interest to verify explicitly that the Euler equation for the maximizing $g$ is indeed Eq. (4a). Let us study the maximization of the functional

$$
J_{m}(g)=2 \int_{0}^{1} \sqrt{m q^{m-1} F g h} d q
$$

where $h=-g^{\prime}>0$ subject to

$$
\int_{0}^{1} g(q) d q=1
$$

The Euler equation for this problem is

$$
\lambda+\left(\frac{m q^{m-1} F h}{g}\right)^{1 / 2}+\frac{d}{d q}\left[\frac{m q^{m-1} F g}{h}\right)=0
$$

where $\lambda$ is the Lagrange multiplier. Using the expression given in Eq. (9c) for $h$ we see that this is exactly Eq. (4a) with the Lagrange multiplier $\lambda=-c^{*}$.

As an application we shall consider the case $F(q)=q(1-q)$ and $m=2$ for which the exact solution is known. Take as the trial function $g(q)=(1-q)^{2}$. Then we obtain

$$
c^{*} \geq 4 \frac{\int_{0}^{1} q(1-q)^{2} d q}{\int_{0}^{1}(1-q)^{2} d q}=1
$$

the exact value, which shows that this is the function $g$ for which the maximum is attained. In addition, due to the existence of the variational principle we may use the Feynman-Hellman formula to calculate the dependence of $c^{*}(m)$ on parameters of $F$. We illustrate this by applying it to the calculation of $d c^{*} / d m$ at $m=2$. Taking the derivative of Eq. (10) with respect to $m$ we obtain

$$
\frac{d c^{*}}{d m}=\frac{1}{\int_{0}^{1} g d q} \int_{0}^{1} \frac{g h F}{\sqrt{m F q^{m-1}} g h}\left[q^{m-1}(1+m \log q)\right] d q
$$

Evaluating at $m=2$, with $g(q)=(1-q)^{2}$, we obtain

$$
\frac{d c^{*}}{d m}(2)=3 \int_{0}^{1} q(1-q)^{2}(1+2 \log q) d q=-\frac{7}{24}
$$

the value previously obtained by other methods $[9,10]$.
A fast estimation of the speed for other values of $m$ can be obtained with simple trial functions. In Fig. 1 we show lower bounds for $F=q(1-q)$ using as trial functions $g_{1}=(1-q)^{2}$ and $g_{2}=(1-q)$. With the first trial function we have the exact value at $m=2$. The dotted line is the line of slope $-\frac{7}{24}$ that coincides with the tangent at $m=2$. For larger $m$ a better estimate is obtained using $g_{2}$. The dashed line is the curve $\sqrt{2 / m}$, which has been suggested by Newman [1] as the best fit to his numerical results. With better choice of trial functions the exact value can be approached arbitrarily close.

Finally we observe that the case $m=1$ when $F^{\prime}(0)=0$ follows directly here. Repeating the procedure starting now from Eq. (10), one obtains

$$
c^{*}=\max 2 \frac{\int_{0}^{1} \sqrt{F g h} d q}{\int_{0}^{1} g d q},
$$

where the maximum is taken over all functions $g$ such that

$$
g(0)=1, g(1)=0, \text { and } h=-g^{\prime}>0
$$

To show this we have used $v^{\prime} / v=c^{*} / p$ and $g=1 / v^{\prime}$ and


FIG. 1. Estimation of the asymptotic speed $c^{*}(m)$ for $F(u)=u(1-u)$. The dashed line corresponds to the fit $\sqrt{2 / m}$ obtained previously from numerical integrations of the initial value problem. The solid lines are approximate values obtained using as trial functions $g_{1}=(1-u)^{2}$ and $g_{2}=1-u$. The dotted line is the calculated slope at $m=2$.
the asymptotic behavior described above.
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